

**Linear Algebra**  
**Math 254**  
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Review for first exam  
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**Solving Linear Systems.** Know how to:

- Transform a system of linear equations into a matrix equation.
- Transform a traffic flow problem into a linear system, and then into a matrix equation.
- Solve a system using Gaussian elimination.
- Explain the steps that you use (row replacement steps and row exchange steps).
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- Write a vector  $x$  as a sum of vectors  $v_1, \dots, v_m$  (or check that it can't be done) using Gaussian elimination.
- Check whether vectors  $v_1, \dots, v_n$  are linearly independent using Gaussian elimination.
- Invert a matrix using Gaussian elimination.

**The Language of Linear Transformations.** Let  $T : \mathbb{R}^n \longrightarrow \mathbb{R}^m$  be the linear transformation given by the  $m \times n$  matrix  $A$ . Let  $b \in \mathbb{R}^m$ .

- Be able to translate transformations on  $\mathbb{R}^2$ , stated as rotations, reflections, or dilations/contractions into matrix form. Be able to work with diagrams of the image of a transformation  $\mathbb{R}^2 \longrightarrow \mathbb{R}^2$  (§1.9#1-14).
- The set of  $x$  satisfying  $T(x) = b$  is the same set as the set of  $x$  satisfying  $Ax = b$ . be able to translate back and forth between the two: (§1.9#17-28).
- **Theorem 6:** Let  $p$  be one solution to  $Ax = b$ . The solution set of  $Ax = b$  is all  $p + v_h$  where  $v_h$  varies among the solutions to  $Ax = 0$ .
- **Theorem 11:**  $T$  is a one-to one function if and only if the only solution to  $Ax = 0$  is the zero vector in  $\mathbb{R}^n$ . [This follows directly from Theorem 6. When there is only one homogeneous solution, there is at most one solution to  $Ax = b$ .]
- There are many ways to express the same essential idea. In the following table, as you read across each row you see different ways of saying a particular concept. The final line contains most of the Invertible Matrix Theorem (Theorem 8 in Chapter 2).

Table 1: Equivalent properties for an  $m \times n$  matrix  $A$ 

$Ax = b$ has a solution for all $b \in \mathbb{R}^m$	RREF of $A$ has a pivot in each row	The columns of $A$ span $\mathbb{R}^m$	The linear transformation $x \mapsto Ax$ is <i>onto</i>	There is an $m \times m$ matrix $Z$ such that $ZA = I_m$	Note: $n \geq m$
$Ax = 0$ has one solution, $x = 0$	RREF of $A$ has a pivot in each column	The columns of $A$ are linearly independent in $\mathbb{R}^m$	The linear transformation $x \mapsto Ax$ is <i>one-to-one</i>	There is an $n \times n$ matrix $Z$ such that $AZ = I_n$	Note: $n \leq m$
$Ax = b$ has exactly one solution for each $b \in \mathbb{R}^m$	RREF of $A$ has a pivot in each row and each column	The columns of $A$ are linearly independent and span $\mathbb{R}^m$	The linear transformation $x \mapsto Ax$ is <i>one-to-one</i> and it onto	there is a $n \times n$ matrix $Z$ such that $AZ = ZA = I_n$	Note: $n = m$